## Lecture 6: Data-Flow Analysis Algorithm: Termination, Complexity, and Fixed Point

17-355/17-665/17-819: Program Analysis Rohan Padhye September 16, 2025

\* Course materials developed with Jonathan Aldrich and Claire Le Goues





## Worklist Algorithm [Kildall'73]

```
worklist = Ø
for Node n in cfg
    input[n] = output[n] = \bot
    add n to worklist
input[0] = initialDataflowInformation
while worklist is not empty
    take a Node n off the worklist
    output[n] = flow(n, input[n])
    for Node j in succs(n)
          newInput = input[j] ⊔ output[n]
          if newInput ≠ input[j]
                input[j] = newInput
                add j to worklist
```

## Ascending Chains & Lattice Height

**Ascending Chain** 

A sequence  $\sigma_k$  is an ascending chain iff  $n \leq m$  implies  $\sigma_n \subseteq \sigma_m$ 

We can define the height of an ascending chain, and of a lattice, in order to bound the number of new analysis values we can compute at each program point:

Height of an Ascending Chain

An ascending chain  $\sigma_k$  has finite height h if it contains h+1 distinct elements.

**Height of a Lattice** 

A lattice  $(L, \sqsubseteq)$  has finite height h if there is an ascending chain in the lattice of height h, and no ascending chain in the lattice has height greater than h

## Worklist Algorithm [Kildall'73]

```
worklist = Ø
for Node n in cfg
    input[n] = output[n] = \bot
    add n to worklist
input[0] = initialDataflowInformation
                                                    O(c * n * h) + O(c * e * h)
while worklist is not empty |O(n * h)|
                                                    = O(c * (e + n) * h)
    take a Node n off the worklist
    output[n] = |flow(n, input[n])| O(c)
    for Node j in succs (n) |0(e * h)| in total (across the while loop)
           newInput = |input[j] \( \to \) output[n] |
            if newInput ≠ input[j]
                                            O(n * h)
                   input[j] = newInput
                   add j to worklist
```

## Worklist Algorithm [Kildall'73]

```
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    output[n] = flow(n, input[n])
    for Node j in succs(n)
          newInput = input[j] ⊔ output[n]
          if newInput ≠ input[j]
                input[j] = newInput
                add j to worklist
```

## Worklist Algorithm [Kam & Ullman'76]

```
worklist = Ø
                                             More obviously computes the fixed point
for Node n in cfg
    input[n] = output[n] = \bot
    add n to worklist
output[programStart] = initialDataflowInformation
while worklist is not empty
    take a Node n off the worklist
    input[n] = \sqcup_{k \in preds(n)} output[k]
    newOutput = flow(n, input[n])
    if newOutput ≠ output[n]
         output[n] = newOutput
         for Node j in succs(n)
```

add j to worklist



## Recall: Fixed point of Flow Functions

$$(\sigma_0, \sigma_1, \sigma_2, \dots, \sigma_n) \xrightarrow{f_z} (\sigma'_0, \sigma'_1, \sigma'_2, \dots, \sigma'_n)$$

Fixed point!

$$(\sigma_0, \sigma_1, \sigma_2, \dots, \sigma_n) = f_z(\sigma_0, \sigma_1, \sigma_2, \dots, \sigma_n)$$

#### **Correctness theorem:**

If data-flow analysis is well designed\*, then any fixed point of the analysis is sound.

\* Lattice has finite height and flow functions are monotonic.

$$\sigma'_{0} = \sigma_{0}$$

$$\sigma'_{1} = f_{z}[x := 10](\sigma_{0})$$

$$\sigma'_{2} = f_{z}[y := 0](\sigma_{1})$$

$$\sigma'_{3} = \sigma_{2} \sqcup \sigma_{7}$$

$$\sigma'_{4} = f_{z}[if x = 10 \text{ goto } 7]_{F}(\sigma_{3})$$

$$\vdots$$

$$\sigma'_{8} = f_{z}[if x = 10 \text{ goto } 7]_{T}(\sigma_{3})$$

$$\sigma'_{9} = f_{z}[x := y](\sigma_{8})$$

## Monotonicity of Flow Functions

#### Monotonicity

A function f is monotonic iff  $\sigma_1 \sqsubseteq \sigma_2$  implies  $f(\sigma_1) \sqsubseteq f(\sigma_2)$ 

For Zero-Analysis:

Case 
$$f_Z[x := 0](\sigma) = \sigma[x \mapsto Z]$$
:

Case 
$$f_Z[x := y](\sigma) = \sigma[x \mapsto \sigma(y)]$$
: Exercise!

## Worklist Algorithm [Kam & Ullman'76]

```
worklist = Ø
                                              Can prove termination using induction!
for Node n in cfg
                                              (assuming monotonic flow functions)
    input[n] = output[n] = \bot
    add n to worklist
output[programStart] = initialDataflowInformation
while worklist is not empty
    take a Node n off the worklist
    input[n] = \sqcup_{k \in preds(n)} output[k]
    newOutput = flow(n, input[n])
    if newOutput ≠ output[n]
         output[n] = newOutput
         for Node j in succs(n)
            add j to worklist
```

# Successive applications for the whole-program flow function results in an ascending chain i.e., $\Sigma \sqsubseteq F(\Sigma)$

Base case: 
$$(\bot, \bot, ..., \bot) \xrightarrow{F} (\sigma'_1, \sigma'_2, ..., \sigma'_n)$$

Inductive case: 
$$(\sigma_1, \sigma_2, ..., \sigma_n) \xrightarrow{F} (\sigma'_1, \sigma'_2, ..., \sigma'_n)$$

Since the height of the composite lattice of tuples  $(\sigma_0, \sigma_1, \sigma_2, ..., \sigma_n)$  is finite, the algorithm terminates! Max number of steps is the height of the composite lattice, which is  $n \times n$  height of the  $\sigma$  lattice, as before.

## Fixed Point

Let  $\mathcal{F}(\langle \sigma_1, \sigma_2, .... \sigma_{|P|} \rangle) = \langle \sigma'_1, \sigma'_2, .... \sigma'_{|P|} \rangle$  be a composite flow function for program P, such that:

$$\forall 1 < i \leqslant |\mathbf{P}| : \sigma_i' = \left( \bigsqcup_{j \in \mathtt{preds}(i)} f[\![P[j]]\!](\sigma_j) \right)$$

$$\sigma_1' = \left( \bigsqcup_{j \in \mathtt{preds}(1)} f[\![P[j]]\!](\sigma_j) \right) \sqcup \sigma_0$$

where  $\sigma_0$  is the initial dataflow information. Then, a dataflow analysis result  $\Sigma = \langle \sigma_1, \sigma_2, .... \sigma_{|P|} \rangle$  is a *fixed point* iff  $\mathcal{F}(\Sigma) = \Sigma$ .

### Worklist Algorithm Terminates at Fixed Point

At the fixed point, we therefore have the following equations satisfied:

$$\sigma_0 \sqsubseteq \sigma_1$$
 $orall i \in P: \left( \bigsqcup_{j \in \mathtt{preds}(i)} f\llbracket P[j] \rrbracket(\sigma_j) \right) \sqsubseteq \sigma_i$ 

The worklist algorithm shown above computes a fixed point when it terminates. We can prove this by showing that the following loop invariant is maintained:

$$\forall i . (\exists j \in preds(i) \text{ such that } f[P[j]](\sigma_i) \not\sqsubseteq \sigma_i) \Rightarrow i \in \text{worklist}$$